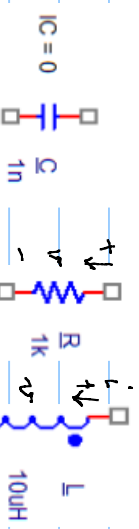


Homework #1 new due date: Tu 09/15/20  
choose base papers soon, you can change later

Generic branch,  $v_b = v_s + v$  and  $i_b = i_s + i$   
device laws: linear  $Av = Bi$

KVL & KCL:  $Q_c = C^T v_b$ ,  $Q_r = -\delta^T v_b$ ,  $v_b = C^T v_c$ ,  $i_b = \delta^T i_c$   
 $e = [1, K]$   $\delta = [-K^T, 1]$  if tree is # first; branches for

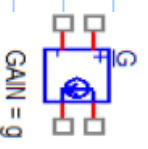
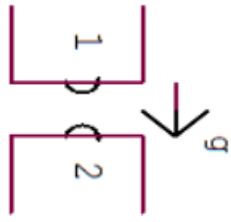
admittance matrix  $Y, i = Yv$



$i = dQ/dt$   
 $Q = C v$   
 $i = C dv/dt$   
 $v = C dv/dt$   
 $a = dv/dt$

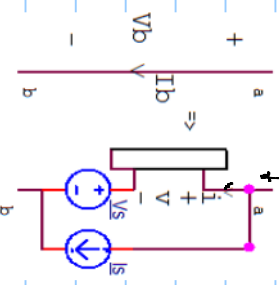
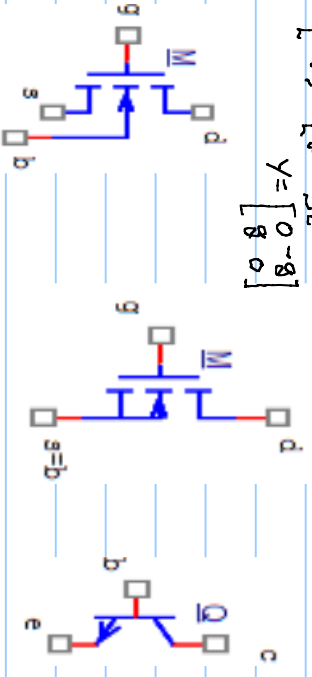
$G = 1/R$   
 $i = G v$   
 $v = R i$

$N = L di/dt$   
 $v = L di/dt$

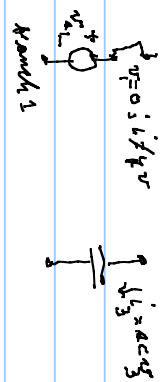
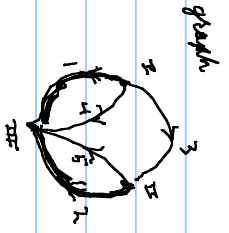
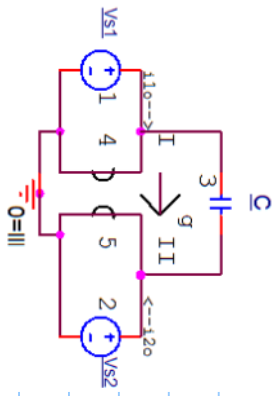


VCCS=OTA=G of Spice  $i_1=0, i_2=Gv_1$

gyrator:  $i_1 = -gV_2, i_2 = gV_1$   
 $\begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} 0 & -g \\ g & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$   
 $Y = \begin{bmatrix} 0 & -g \\ g & 0 \end{bmatrix}$



Ideal linearized transistors:  
MOS:  $i_d = g_m v_{gs}$  &  $i_g = 0$ ; BJT  $\Rightarrow i_c = (\beta + 1) i_b$  &  $v_{be} = 0 \Rightarrow i_b = 0$   
nonlinear both use models



Richards' section  
(2-port)

$$i_N = -g v_s$$

$$i_T = g v_N$$

$$A v = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & ac & 0 & 0 \\ 0 & 0 & 0 & 0 & -g \\ 0 & 0 & 0 & g & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} i_1 \\ i_2 \\ i_3 \\ i_4 \\ i_5 \end{bmatrix}$$

$$v = v_b - v_a$$

$$i = i_b - i_a$$

$$\text{Max } i_a = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, v_a = \begin{bmatrix} v_{a1} \\ v_{a2} \\ v_{a3} \\ v_{a4} \\ v_{a5} \end{bmatrix}$$

$$A(v_b - v_a) = B(i_b - i_a)$$

$$A(G_{21}) - A v_a = B(G^T) i - B i_a$$

$$A E v_b - B G^T i_a = A v_a - B i_a$$

$$\text{eqn } \begin{cases} b \\ \end{cases} \begin{bmatrix} A E^T & -B G^T \\ \end{bmatrix} \begin{bmatrix} v_b \\ i_a \end{bmatrix} = \begin{bmatrix} A v_a - B i_a \\ \end{bmatrix}$$

$\underbrace{\hspace{10em}}_{\text{matrix}}$ 
 $\underbrace{\hspace{10em}}_{\text{forcing function}}$ 
 $\underbrace{\hspace{10em}}_{\text{matrix}}$ 
 $\underbrace{\hspace{10em}}_{\text{matrix}}$



$$E: \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & -1 & 0 & 1 \end{bmatrix} v_b$$

$$G: \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 & +1 & 1 & 0 & 0 \\ -1 & 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & -1 & 0 \end{bmatrix} i_b$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & ac & 0 & 0 \\ 0 & 0 & 0 & 0 & -g \\ 0 & 0 & 0 & g & 0 \end{bmatrix} \begin{bmatrix} v_{a1} \\ v_{a2} \\ v_{a3} \\ v_{a4} \\ v_{a5} \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & ac & 0 & 0 \\ 0 & 0 & 0 & 0 & -g \\ 0 & 0 & 0 & g & 0 \end{bmatrix} \begin{bmatrix} v_b \\ i_a \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ ac & -g \\ g & 0 \end{bmatrix} = A E^T$$

$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & +1 & 1 & 0 & 0 \\ -1 & 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & -1 & 0 \end{bmatrix} = B G^T$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ AC-kC & -1 & 0 & 0 & 0 \\ 0 & -g & 0 & -1 & 0 \\ g & 0 & 0 & 0 & -1 \end{bmatrix} x = \begin{bmatrix} v_{s1} \\ v_{s2} \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

nodal equations  
 nodes x; inputs =

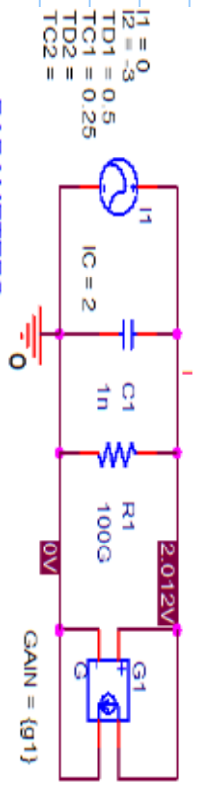
$$x = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \end{bmatrix}$$

outputs =  $\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \end{bmatrix}$

$$\begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ AC-kC & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} x + \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_{s1} \\ v_{s2} \\ -i_1 \\ -i_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} x = i_0$$

$$\begin{cases} \dot{x} = Ax + Bu \\ y = Cx \end{cases}$$

$u = \text{inputs}$   
 $x = \text{states}$   
 $y = \text{outputs}$



PARAMETERS:

$$g1 = -1$$

$$G1dV(I)/dt = -g1V1 - I_s1 - (1/R) V(I)$$